# A REMARK ON A TRIPLE POINTS IN THE BOUNDARY OF QUATERNIONIC HYPERBOLIC SPACE 

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#### Abstract

In this paper we consider a triple of distinct points in the boundary of quaternionic hyperbolic space and detect where these points are by using the quaternionic triple product.


## 1. Introduction

When a triple of distinct points are given on the boundary of quaternionic hyperbolic space, by using the Cartan angular invariant, one can determine whether these three points lie in a same $\mathbb{R}$-circle or in the boundary of $\mathbb{H}$-line.(See [1]) More precisely, B.Apanasov and I.Kim proved the following theorem.

Theorem 1.1. (Theorem 3.5 and 3.6 in [1]) A triple $x=\left(x_{1}, x_{2}, x_{3}\right) \in$ $\left(\partial \mathbf{H}_{\mathbb{H}}^{\mathbf{n}}\right)^{3}$ lies in the boundary of an $\mathbb{H}$-line if and only if $\mathbb{A}_{\mathbb{H}}(p)=\pi / 2$, and lies in the same $\mathbb{R}$-circle if and only if $\mathbb{A}_{\mathbb{H}}(p)=0$.

Here $\mathbb{A}_{\mathbb{H}}(p)=\pi / 2$ if and only if $\left\langle\tilde{x}_{1}, \tilde{x}_{2}, \tilde{x}_{3}\right\rangle$ is purely imaginary and $\mathbb{A}_{\mathbb{H}}(p)=0$ if and only if $\left\langle\tilde{x}_{1}, \tilde{x}_{2}, \tilde{x}_{3}\right\rangle \in \mathbb{R}$ respectively.(We will define the Cartan angular invariant $\mathbb{A}_{\mathbb{H}}(p)$ and the triple $\left\langle\tilde{x}_{1}, \tilde{x}_{2}, \tilde{x}_{3}\right\rangle$ in next chapter.)
In this article, we give answer to the question that where these three
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points are when the triple $\left\langle\tilde{x}_{1}, \tilde{x}_{2}, \tilde{x}_{3}\right\rangle$ is other values such as a complex number or of the form $a+b j$ or $a+b k$ where $a, b \in \mathbb{R}$.

## 2. Quaternionic Cartan angular invariant

The projective model of the quaternionic hyperbolic space $H_{\mathbb{H}}^{n}$ is the set of negative lines in the Hermitian vector space $\mathbb{H}^{n, 1}$ with Hermitian structure defined by the indefinite ( $n, 1$ )-form

$$
\langle\langle z, w\rangle\rangle=z_{1} \overline{w_{1}}+\cdots+z_{n} \overline{w_{n}}-z_{n+1} \overline{w_{n+1}} .
$$

One can obtain the ball model $B_{\mathbb{H}}^{n}(0,1) \subset \mathbb{H}^{n}$ by taking inhomogeneous coordinates. Here, throughout this article, we use the left vector space $\mathbb{H}^{n, 1}$, in which multiplication by quaternion numbers is on the left. For more details on quaternionic hyperbolic geometry, we refer [1], [3] or [4]. The Cartan angular invariant is well-known invariant in complex hyperbolic geometry, but in quaternionic hyperbolic geometry, B.N.Apanasov and I.Kim first defined it in [1]. Here we give the definition and some properties.
Let $x=\left(x_{1}, x_{2}, x_{3}\right) \in\left(H_{\mathbb{H}}^{n} \cup \partial H_{\mathbb{H}}^{n}\right)^{3}$ be a triple of distinct points with lifts $\tilde{x}_{i} \in H_{\mathbb{H}}^{n, 1}$ for $i=1,2,3$. Then the quaternionic Cartan angular invariant $\mathbb{A}_{\mathbb{H}}(x)$ of a triple $x=\left(x_{1}, x_{2}, x_{3}\right)$ is the angle between the first coordinate line $\mathbb{R} e_{0}=(\mathbb{R}, 0,0,0) \subset \mathbb{R}^{4} \cong \mathbb{H}$ and the radius vector of the quaternion equal to the Hermitian triple product $\left\langle\tilde{x}_{1}, \tilde{x}_{2}, \tilde{x}_{3}\right\rangle=\left\langle\tilde{x}_{1}, \tilde{x}_{2}\right\rangle\left\langle\tilde{x}_{2}, \tilde{x}_{3}\right\rangle\left\langle\tilde{x}_{3}, \tilde{x}_{1}\right\rangle \in \mathbb{H}$. We list some properties of this invariant. One can check them easily or find the proofs in [1].
(1) $\mathbb{A}_{\mathbb{H}}(x)$ is independent of the choice of the lifts $\tilde{x}_{i}$ of the $x_{i}$.
(2) $\mathbb{A}_{\mathbb{H}}(x)$ is invariant under permutations of the points $x_{i}$.
(3) For $x=\left(x_{1}, x_{2}, x_{3}\right)$ and $y=\left(y_{1}, y_{2}, y_{3}\right), \mathbb{A}_{\mathbb{H}}(x)=\mathbb{A}_{\mathbb{H}}(y)$ if and only if there exists an isometry $f \in \mathbf{P S p}(n, 1)$ of $H_{\mathbb{H}}^{n}$ such that $f\left(x_{i}\right)=y_{i}$ for $i=1,2,3$.
In addition, B.Apanasov and I.Kim showed the following theorems.
Theorem 2.1. (Theorem 3.5 in [1]) A triple $x=\left(x_{1}, x_{2}, x_{3}\right) \in\left(\partial H_{\mathbb{H}}^{n}\right)^{3}$ lies in the same $\mathbb{R}$-circle if and only if $\mathbb{A}_{\mathbb{H}}(x)=0$.

Theorem 2.2. (Theorem 3.6 in [1]) A triple $x=\left(x_{1}, x_{2}, x_{3}\right) \in\left(\partial H_{\mathbb{H}}^{n}\right)^{3}$ lies in the boundary of an $\mathbb{H}$-line if and only if $\mathbb{A}_{\mathbb{H}}(x)=\pi / 2$.

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Remark 2.3. In the above theorems, $\mathbb{A}_{\mathbb{H}}(x)=0$ means that $\left\langle\tilde{x}_{1}, \tilde{x}_{2}, \tilde{x}_{3}\right\rangle \in$ $\mathbb{R}$ and $\mathbb{A}_{\mathbb{H}}(x)=\pi / 2$ means that $\left\langle\tilde{x}_{1}, \tilde{x}_{2}, \tilde{x}_{3}\right\rangle$ is purely imaginary.

## 3. Main theorem

From now on, we will focus on the triple product $\left\langle\tilde{x}_{1}, \tilde{x}_{2}, \tilde{x}_{3}\right\rangle$ instead of $\mathbb{A}_{\text {Hit }}$.

Theorem 3.1. Let $K=\left\{\left(q_{1}, q_{2}\right) \in H_{\mathbb{H}}^{2} \mid q_{1} \in \mathbb{H}, q_{2} \in \mathbb{C}\right\}$. Then a triple points $x_{1}, x_{2}, x_{3} \in \partial H_{\mathbb{H}}^{2}$ lies in a copy of $K$ if and only if the triple product $\left\langle\tilde{x}_{1}, \tilde{x}_{2}, \tilde{x}_{3}\right\rangle \in \mathbb{C}$.

Proof. First, assume that $x_{1}, x_{2}, x_{3} \in \partial H_{\mathbb{H}}^{2}$ lies in a copy of $K$. Without loss of generality, we may assume that $x_{1}=(0,-1), x_{2}=(0,1), x_{3}=$ $\left(q_{1}, q_{2}\right)$, where $q_{1} \in \mathbb{H}, q_{2} \in \mathbb{C}$ and $\left|q_{1}\right|^{2}+\left|q_{2}\right|^{2}=1$. Then $\left\langle\tilde{x}_{1}, \tilde{x}_{2}, \tilde{x}_{3}\right\rangle=$ $-2\left(\bar{q}_{2}-1\right)\left(-q_{2}-1\right)=-2\left\{\left|q_{1}\right|^{2}+\left(q_{2}-\bar{q}_{2}\right)\right\} \in \mathbb{C}$.
Conversely, up to isometry, we can assume that $x_{1}=(0,-1), x_{2}=$ $(0,1), x_{3}=\left(q_{1}, q_{2}\right)$ for $q_{1}, q_{2}$ are quaternions, $\left|q_{1}\right|^{2}+\left|q_{2}\right|^{2}=1$ and $\tilde{x}_{1}=$ $(0,-1,1), \tilde{x}_{2}=(0,1,1), \tilde{x}_{3}=\left(q_{1}, q_{2}, 1\right)$. Then $\left\langle\tilde{x}_{1}, \tilde{x}_{2}, \tilde{x}_{3}\right\rangle=-2\left(\left|q_{1}\right|^{2}+\right.$ $\left.2 \operatorname{Im}\left(q_{2}\right)\right) \in \mathbb{C}$, so $q_{2} \in \mathbb{C}$.

Remark 3.2. In the above theorem, when we replace the condition $\left\langle\tilde{x}_{1}, \tilde{x}_{2}, \tilde{x}_{3}\right\rangle \in \mathbb{C}$ with $\left\langle\tilde{x}_{1}, \tilde{x}_{2}, \tilde{x}_{3}\right\rangle$ is of the form $a+b j$ or $a+b k$ for $a, b \in \mathbb{R}$, one can easily checked that $K$ is replaced with $K^{\prime}=\left\{\left(q_{1}, q_{2}\right) \in H_{\mathbb{H}}^{2} \mid q_{1} \in\right.$ $\mathbb{H}, q_{2}$ is of the form $\left.a+b j\right\}$ or $K^{\prime \prime}=\left\{\left(q_{1}, q_{2}\right) \in H_{\mathbb{H}}^{2} \mid q_{1} \in \mathbb{H}, q_{2}\right.$ is of the form $a+b k\}$

Remark 3.3. In the theorem, the set $K$ is similar to the bisector in the complex hyperbolic space.(See [2])

The following theorem is a special case of Theorem 2.2 and also a special case of the above theorem. By the way, it is also analogous of the result in complex hyperbolic Cartan angular invariant.

Theorem 3.4. A triple $x=\left(x_{1}, x_{2}, x_{3}\right) \in\left(\partial H_{\mathbb{H}}^{2}\right)^{3}$ lies in a copy of $H_{\mathbb{C}}^{1}$ if and only if the triple product $\left\langle\tilde{x}_{1}, \tilde{x}_{2}, \tilde{x}_{3}\right\rangle \in \mathbb{R} i$.

Proof. First, assume that a triple $x=\left(x_{1}, x_{2}, x_{3}\right) \in\left(\partial H_{\mathbb{Z}}^{2}\right)^{3}$ lies in a copy of $H_{\mathbb{C}}^{1}$. Without loss of generality, we may assume that $x_{1}, x_{2}, x_{3} \in \partial H_{\mathbb{C}}^{1}$ and $x_{1}=(0,-1), x_{2}=(0,1), x_{3}=(0, z)$, where $|z|=1$, $z \in \mathbb{C}$. Then $\left\langle\tilde{x}_{1}, \tilde{x}_{2}, \tilde{x}_{3}\right\rangle=-2(z-\bar{z}) \in \mathbb{R} i$.

Conversely, up to isometry, we can assume that $x_{1}=(0,-1), x_{2}=$ $(0,1), x_{3}=\left(q_{1}, q_{2}\right)$ for $q_{1}, q_{2}$ are quaternions, $\left|q_{1}\right|^{2}+\left|q_{2}\right|^{2}=1$ and $\tilde{x}_{1}=$ $(0,-1,1), \tilde{x}_{2}=(0,1,1), \tilde{x}_{3}=\left(q_{1}, q_{2}, 1\right)$. Then $\left\langle\tilde{x}_{1}, \tilde{x}_{2}, \tilde{x}_{3}\right\rangle=-2\left(\left|q_{1}\right|^{2}+\right.$ $\left.2 \operatorname{Im}\left(q_{2}\right)\right)$, so $q_{2} \in \mathbb{C}$ since $\left|q_{1}\right|^{2}+2 \operatorname{Im}\left(q_{2}\right) \in \mathbb{R} i$. Hence $q_{1}=0$ and $q_{2} \in \mathbb{C}$, so $x_{3}$ is also in $H_{\mathbb{C}}^{1}$.

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