

## A BIFURCATION PROBLEM FOR THE BIHARMONIC OPERATOR

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ABSTRACT. We investigate the number of the solutions for the biharmonic boundary value problem with a variable coefficient nonlinear term. We get a theorem which shows the existence of  $m$  weak solutions for the biharmonic problem with variable coefficient. We obtain this result by using the critical point theory induced from the invariant function and invariant linear subspace.

### 1. Introduction

Let  $\Omega$  be a bounded domain in  $R^n$  with smooth boundary  $\partial\Omega$ . Let  $\Delta$  be the elliptic operator and  $\Delta^2$  be the biharmonic operator. Let  $c \in R$ ,  $a : \overline{\Omega} \rightarrow R$  be a continuous function and  $g : \overline{\Omega} \rightarrow R$  be a  $C^1$  function. Assume that  $a(x) > 0$  in  $\overline{\Omega}$ . In this paper we investigate the multiplicity of the weak solutions for the following variable coefficient nonlinear biharmonic equation with Dirichlet boundary condition

$$(1.1) \quad \begin{aligned} \Delta^2 u + c\Delta u &= \Lambda(a(x)u + g(u)) && \text{in } \Omega, \\ u = 0, \quad \Delta u &= 0 && \text{on } \partial\Omega. \end{aligned}$$

Let  $\lambda_j$ ,  $j \geq 0$  be the eigenvalues and  $\phi_j$ ,  $j \geq 1$  be the corresponding eigenfunctions suitably normalized with respect to  $L^2(\Omega)$  inner product and each eigenvalue  $\lambda_j$  is repeated as often as its multiplicity, of the eigenvalue problem

$$\Delta u + \lambda u = 0 \quad \text{in } \Omega,$$

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Received May 9, 2012. Revised June 13, 2012. Accepted June 15, 2012.

2010 Mathematics Subject Classification: 35J30, 35J40.

Key words and phrases: biharmonic boundary value problem, critical point theory, invariant function, invariant subspace,  $(P.S.)_c$  condition, eigenvalue problem.

This work(Tacksun Jung) was supported by Basic Science Research Program through the National Research Foundation of Korea(NRF) funded by the Ministry of Education, Science and Technology (KRF-2011-0026920).

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$$u = 0 \quad \text{on } \partial\Omega.$$

The eigenvalue problem

$$\begin{aligned} \Delta^2 u + c\Delta u &= \mu a(x)u && \text{in } \Omega, \\ u = 0, \quad \Delta u &= 0 && \text{on } \partial\Omega, \end{aligned}$$

has also infinitely many eigenvalues  $\mu_j = \lambda_j(\lambda_j - c)$ ,  $j \geq 1$  and corresponding eigenfunctions  $\psi_j$ ,  $j \geq 1$ . We note that  $\mu_1 < \mu_2 \leq \mu_3 \dots$ ,  $\mu_j \rightarrow +\infty$ .

We assume that  $g$  satisfies the following conditions:

(g1)  $g \in C^1(R, R)$  and  $g(\xi) = o(|\xi|)$  uniformly with respect to  $x \in \bar{\Omega}$ .

(g2)  $g(\xi) < 0$  for any  $\xi \in R$ .

(g3)  $g(u) = -g(-u)$  for any  $u \in \bar{\Omega}$ .

Jung and Choi [4] showed the existence of at least two solutions, one of which is bounded solution and large norm solution of (1.1) when  $g(u)$  is polynomial growth or exponential growth nonlinear term. The authors proved this result by the variational method and the mountain pass theorem. For the constant coefficient nonlinear case Choi and Jung [3] showed that the problem

$$(1.2) \quad \begin{aligned} \Delta^2 u + c\Delta u &= bu^+ + s && \text{in } \Omega, \\ u = 0, \quad \Delta u &= 0 && \text{on } \partial\Omega, \end{aligned}$$

has at least two nontrivial solutions when ( $c < \lambda_1$ ,  $\Lambda_1 < b < \Lambda_2$  and  $s < 0$ ) or ( $\lambda_1 < c < \lambda_2$ ,  $b < \Lambda_1$  and  $s > 0$ ). The authors obtained these results by use of the variational reduction method. The authors [5] also proved that when  $c < \lambda_1$ ,  $\Lambda_1 < b < \Lambda_2$  and  $s < 0$ , (1.2) has at least three nontrivial solutions by use of the degree theory. Tarantello [9] also studied the problem

$$(1.3) \quad \begin{aligned} \Delta^2 u + c\Delta u &= b((u+1)^+ - 1) && \text{in } \Omega, \\ u = 0, \quad \Delta u &= 0 && \text{on } \partial\Omega. \end{aligned}$$

She show that if  $c < \lambda_1$  and  $b \geq \Lambda_1$ , then (1.3) has a negative solution. She obtained this result by the degree theory. Micheletti and Pistoia [7] also proved that if  $c < \lambda_1$  and  $b \geq \Lambda_2$ , then (1.3) has at least four solutions by the variational linking theorem and Leray-Schauder degree

theory. The authors [6] investigate the multiple solutions of semilinear elliptic equations. In this paper we are trying to find weak solutions of (1.1), that is,

$$\int_{\Omega} [\Delta^2 u \cdot v + c \Delta u \cdot v - \Lambda(a(x)u + g(u))v] dx = 0, \quad \forall v \in H,$$

where  $H$  is introduced in section 2.

Our main result is the following.

**THEOREM 1.1.** *Let  $\lambda_j < c < \lambda_{j+1}$ . Assume that  $a(x) > 0$  and  $g$  satisfies the conditions (g1) – g(3). If  $\mu_k < \Lambda < \mu_{k+1}$ ,  $k \geq j + 1$ , then (1.1) has at least  $k$  weak solutions.*

We prove Theorem 1.1 by the critical point theory induced from the invariant subspace and invariant functional. The outline of the proof of Theorem 1.1 is as follows: In section 2, we introduce a Hilbert space  $H$  and a closed invariant linear subspace  $X$  of  $H$  which is invariant under the operator  $u \mapsto \int_{\Omega} |\Delta u|^2 - c|\nabla u|^2 dx$ , the invariant subspaces of  $X$  and the invariant function on  $X$ . We obtain some results on the norm  $\|\cdot\|$  and the functional  $f(u)$ , and recall a critical point theory in terms of the invariant functional and invariant subspaces which plays a crucial role for the proof of the main result. In section 3, we prove Theorem 1.1.

## 2. Critical point theory induced from the invariant subspace and the invariant function

Let  $L^2(\Omega)$  be a square integrable function space defined on  $\Omega$ . Any element  $u$  in  $L^2(\Omega)$  can be written as

$$u = \sum h_k \phi_k \quad \text{with} \quad \sum h_k^2 < \infty.$$

We define a subspace  $H$  of  $L^2(\Omega)$  as follows

$$H = \{u \in L^2(\Omega) \mid \sum |\mu_k| h_k^2 < \infty\}.$$

Then this is a complete normed space with a norm

$$\|u\| = [\sum |\mu_k| h_k^2]^{\frac{1}{2}}.$$

Since  $\lambda_k \rightarrow +\infty$  and  $c$  is fixed, we have

- (i)  $\Delta^2 u + c\Delta u \in H$  implies  $u \in H$ .
- (ii)  $\|u\| \geq C\|u\|_{L^2(\Omega)}$ , for some  $C > 0$ .
- (iii)  $\|u\|_{L^2(\Omega)} = 0$  if and only if  $\|u\| = 0$ ,

which is proved in [2].

Let

$$H^+ = \{u \in H \mid h_k = 0 \text{ if } \mu_k < 0\},$$

$$H^- = \{u \in H \mid h_k = 0 \text{ if } \mu_k > 0\}.$$

Then  $H = H^- \oplus H^+$ , for  $u \in H$ ,  $u = u^- + u^+ \in H^- \oplus H^+$ . Let  $P_+$  be the orthogonal projection on  $H^+$  and  $P_-$  be the orthogonal projection on  $H^-$ . We can write  $P_+u = u^+$ ,  $P_-u = u^-$ , for  $u \in H$ . We are looking for the weak solutions of (1.1). By the following Proposition 2.1, the weak solutions of (1.1) coincide with the critical points of the associated functional

$$I(u) \in C^1(H, R),$$

$$(2.1) \quad \begin{aligned} I(u) &= \int_{\Omega} \left[ \frac{1}{2} |\Delta u|^2 - \frac{c}{2} |\nabla u|^2 - \Lambda \int_{\Omega} \left[ \frac{1}{2} a(x) u^2 + G(u) \right] dx \right. \\ &= \frac{1}{2} (\|P_+u\|^2 - \|P_-u\|^2) - \Lambda \int_{\Omega} \left[ \frac{1}{2} a(x) u^2 + G(u) \right] dx, \end{aligned}$$

where  $G(\xi) = \int_0^{\xi} g(\tau) \tau$ . By (g1),  $I$  is well defined.

**PROPOSITION 2.1.** *Assume that  $\lambda_j < c < \lambda_{j+1}$ ,  $j \geq 1$ , and  $g$  satisfies (g1) – (g3). Then  $I(u)$  is continuous and Fréchet differentiable in  $H$  with Fréchet derivative*

$$(2.2) \quad \nabla I(u)h = \int_{\Omega} [\Delta u \cdot \Delta h - c \nabla u \cdot \nabla h - \Lambda(a(x)u + g(u))h] dx.$$

If we set

$$F(u) = \Lambda \int_{\Omega} \left[ \frac{1}{2} a(x) u^2 + G(u) \right] dx,$$

then  $F'(u)$  is continuous with respect to weak convergence,  $F'(u)$  is compact, and

$$F'(u)h = \Lambda \int_{\Omega} (a(x)u + g(u))h dx \quad \text{for all } h \in H,$$

this implies that  $I \in C^1(H, R)$  and  $F(u)$  is weakly continuous.

The proof of Proposition 2.1 has the similar process to that of the proof in Appendix B in [8].

Let us define some notations and concepts on  $Z_2$ -invariant set and  $Z_2$ -invariant function: Let  $H$  be a real Hilbert space on which the action  $Z_2$  acts orthogonally. For  $u \in H$ , we define  $Z_2$ -actions on  $H$  by

$$Tu = u \quad \text{or} \quad Tu = -u.$$

that is, the  $Z_2$  action have the identity map and the antipodal map as an action. Thus  $Z_2$ -action acts freely on the subspace  $\{u \mid Tu = -u\}$ . Let  $\text{Fix}_{Z_2}$  be the set of fixed points of the action, i.e.,

$$\text{Fix}_{Z_2} = \{u \in H \mid Tu(x) = u(x), \text{ for all } x \in \Omega, u \in H, Z_2\text{-action } T\}.$$

We note that  $\text{Fix}_{Z_2} = \{0\}$ . Let

$$X_1 = \text{Fix}_{Z_2} = \{0\} \quad X_2 = X_1^\perp.$$

Thus  $Z_2$ -action has the representation  $x \mapsto -x$ , for  $x \in X_2$  and  $H = X_1 \oplus X_2$ . We say a subset  $B$  of  $H$  an  $Z_2$ -invariant set if for all  $u \in B$ ,  $Tu \in B$ . A function  $I : H \rightarrow R^1$  is called  $Z_2$ -invariant if  $I(Tu) = I(u)$ ,  $\forall u \in H$ . Let  $C(B, H)$  be the set of continuous functions from  $B$  into  $H$ . If  $B$  is an invariant set we say  $h \in C(B, H)$  is an equivariant map if  $h(Tu) = Th(u)$  for all  $u \in B$ . We note that  $H$  is a closed invariant linear subspace of  $H$  compactly embedded in  $L^2(\Omega, R)$  under the  $Z_2$ -action. Let

$$(Lu)h = \int_{\Omega} [\Delta u \cdot \Delta h - c \nabla u \cdot \nabla h] dx.$$

We can check easily that  $L(H) \subseteq H$ ,  $L : H \rightarrow H$  is an isomorphism and  $\nabla I(H) \subseteq H$ . Therefore constrained critical points on  $H$  are in fact free critical points on  $H$ . Moreover, distinct critical orbits give rise to geometrically distinct solutions. We have the following lemma which can be checked easily since  $\text{Fix}_{Z_2} = \{0\}$ :

LEMMA 2.1. *Assume that  $g$  satisfies the conditions (g1) – (g3). Let  $u \in \text{Fix}_{Z_2} = \{0\}$  and  $u$  be a critical point of the functional of  $I$ , i.e.,  $\nabla I(u) = 0$ . Then  $I(u) = 0$ .*

Now we recall the critical point theory in terms of the invariant subspace and invariant function in Theorem 4.1 of [1] which plays a crucial role for the proof of Theorem 1.1: Let  $S_\rho$  be the sphere centered at the origin of radius  $\rho$ . Let  $I : H \rightarrow R$  be a functional of the form

$$(2.3) \quad I(u) = \frac{1}{2}(Lu)u - F(u),$$

where  $L : H \rightarrow H$  is linear, continuous, symmetric and equivariant,  $F : H \rightarrow R$  is of class  $C^1$  and invariant and  $DF : H \rightarrow H$  is compact.

**THEOREM 2.1.** *Assume that  $I \in C^1(H, R^1)$  is  $Z_2$ -invariant and there exist two closed invariant linear subspaces  $V, W$  of  $H$  and  $\rho > 0$  with the following properties:*

- (a)  $V + W$  is closed and of finite codimension in  $H$ ;
- (b)  $\text{Fix}_{Z_2} \subseteq V + W$ ;
- (c)  $L(W) \subseteq W$ ;
- (d)  $\sup_{S_\rho \cap V} I < +\infty$  and  $\inf_W I > -\infty$ ;
- (e)  $u \notin \text{Fix}_{Z_2}$  whenever  $DI(u) = 0$  and  $\inf_W I \leq I(u) \leq \sup_{S_\rho \cap V} I$ ;
- (f)  $I$  satisfies  $(P.S.)_c$  condition whenever  $\inf_W I \leq c \leq \sup_{S_\rho \cap V} I$ .

Then  $I$  possesses at least

$$\dim(V \cap W) - \text{codim}_H(V + W)$$

distinct critical orbits in  $I^{-1}([\inf_W I, \sup_{S_\rho \cap V} I])$ .

### 3. Proof of Theorem 1.1

To prove Theorem 1.1 we shall prove that the functional  $I$  satisfies the assumptions (g1) – g(3) of Theorem 2.1. We assume that  $g$  satisfies the conditions (g1) – (g3). Let us set

$$H_1^+ = \{u \mid u \in H, u \in \text{span}\{\psi_l, l \geq 1\}\},$$

$$H_k^- = \{u \mid u \in H, u \in \text{span}\{\psi_l, 1 \leq l \leq k\}\}.$$

We have the following lemma which can be checked easily since  $\text{Fix}_{Z_2} = \{0\}$ :

**LEMMA 3.1.** *Assume that  $g$  satisfies the conditions (g1) – (g3). Then there exist  $\rho > 0$  and a sphere  $S_\rho$  centered at 0 in  $H$  such that the*

functional  $I(u)$  is bounded from above on  $S_\rho \cap H_k^-$  and from below on  $H_1^+$ . That is,

$$-\infty < \inf_{u \in H_1^+} I(u) \quad \text{and} \quad \sup_{u \in S_\rho \cap H_k^-} I(u) < 0.$$

*Proof.* We note that

$$(3.1) \quad \begin{aligned} \forall u \in H_k^- : (Lu)u &\leq \mu_k \int_\Omega a(x)u^2 dx, \\ \forall u \in H_1^+ : (Lu)u &\geq \mu_1 \int_\Omega a(x)u^2 dx. \end{aligned}$$

Then for  $u \in H_k^-$ ,

$$(3.2) \quad \begin{aligned} I(u) &= \frac{1}{2}(Lu)u - \Lambda \int_\Omega \left[ \frac{1}{2}a(x)u^2 + G(u) \right] dx \\ &\leq \frac{1}{2}(\mu_k - \Lambda) \int_\Omega a(x)u^2 dx + o(\|u\|_{L^2(\Omega)}^2) \end{aligned}$$

since  $G(\xi) \in C^2$ . Thus we can choose a number  $\rho > 0$  and a sphere  $S_\rho$  centered at 0 in  $H$  such that for any  $u \in S_\rho$ ,

$$(3.3) \quad \begin{aligned} &\frac{1}{2}(\mu_k - \Lambda) \int_\Omega a(x)u^2 dx + o(\|u\|_{L^2(\Omega)}^2) \\ &\leq \frac{1}{2}(\mu_k - \Lambda)(\sup a(x))\rho^2 + o(\|u\|_{L^2(\Omega)}^2) < 0 \end{aligned}$$

since  $\mu_k - \Lambda < 0$ . Thus we have  $\sup_{S_\rho \cap H_k^-} I(u) < 0$ . Let  $u \in H_1^+$ . Then we have

$$\begin{aligned} I(u) &= \frac{1}{2}(Lu)u - \Lambda \int_\Omega \left[ \frac{1}{2}a(x)u^2 + G(u) \right] dx \\ &\geq \frac{1}{2}(\mu_1 - \Lambda) \int_\Omega a(x)u^2 dx + o(\|u\|_{L^2(\Omega)}^2) \\ &> \frac{1}{2}(\mu_1 - \Lambda)(\sup a(x))\|u\|_{L^2}^2 + o(\|u\|_{L^2(\Omega)}^2) \\ &> -\infty \end{aligned}$$

since  $\mu_1 - \Lambda < 0$ ,  $G(u) = o(\|u\|_{L^2(\Omega)}^2)$ .

Thus we have  $\inf_{u \in H_1^+} I(u) > -\infty$ . □

LEMMA 3.2. Assume that  $g$  satisfies the conditions (g1) – (g3). Then the functional  $I$  satisfies  $(P.S.)_c$  condition for every  $c \in [\inf_W I(u), \sup_{S_\rho \cap V} I(u)]$ .

*Proof.* Let  $u \in H$ . Since  $H = H_1^+$ , the functional

$$\begin{aligned}
 (3.4) \quad I(u) &= \frac{1}{2}(Lu)u - \Lambda \int_{\Omega} \left[ \frac{1}{2}a(x)u^2 + G(u) \right] dx \\
 &\geq \frac{1}{2}(\mu_1 - \Lambda) \int_{\Omega} a(x)u^2 dx - \Lambda \int_{\Omega} G(u) dx \\
 &> \frac{1}{2}(\mu_1 - \Lambda) \sup(a(x)) \|u\|_{L^2}^2 - o(\|u\|_{L^2}^2) \\
 &\geq \frac{1}{2}(\mu_1 - \Lambda) \sup(a(x)) \|u\|_{L(\Omega)}^2 - o(\|u\|_{L^2}^2) \\
 &> -\infty.
 \end{aligned}$$

Thus  $I(u)$  is bounded from below since  $G(\xi) = o(|\xi|^2)$ . Thus  $I(u)$  satisfies the  $(P.S.)_c$  condition.  $\square$

[Proof of Theorem 1.1]

If we set  $V = H_k^-$  and  $W = H_1^+ = H$ , then  $V + W$  is closed invariant subspaces of  $H$  with  $V + W = H$  and of finite codimension in  $H$ . We note that  $\text{Fix}_{Z_2} = \{0\}$  and  $\text{Fix}_{Z_2} = \{0\} \subseteq V + W = H$ . We also note that  $L(W) \subseteq W$ . By Lemma 3.1,

$$-\infty < \inf_W I \quad \sup_{H_k^-} \cap S_{\rho} I < 0.$$

Thus the condition (d) of Theorem 2.1 is satisfied. Suppose that  $u$  be a critical point of the functional of  $I$  and  $\inf_W I \leq I(u) \leq \sup_{S_{\rho} \cap V} I$ . Then by Lemma 3.1,  $-\infty < \inf_W I \leq I(u) \leq \sup_{S_{\rho} \cap V} I < 0$ . We claim that  $u \notin \text{Fix}_{Z_2}$ . If not, then  $u \in \text{Fix}_{Z_2} = \{0\}$  i.e.,  $u = 0$ . Since  $u = 0$  is a critical point of  $I(u)$  with  $I(0) = 0$  and  $0 \notin [\inf_W I, \sup_{S_{\rho} \cap V} I]$ , it leads to a contradiction to the fact that  $\inf_W I \leq I(u) \leq \sup_{S_{\rho} \cap V} I$ . Thus  $u \notin \text{Fix}_{Z_2}$ . Thus the condition (e) is satisfied. By Lemma 3.2,  $I$  satisfies  $(P.S.)_c$  condition whenever  $\inf_W I \leq c \leq \sup_{S_{\rho} \cap V} I$ .

Thus the assumptions (a) – (e) of Theorem 1.1 are satisfied. Thus by the Theorem 2.1, Then  $I$  possesses at least

$$\dim(V \cap W) - \text{codim}_H(V + W) = k$$

distinct critical orbits in  $I^{-1}([\inf_W I, \sup_{S_{\rho} \cap V} I])$ .



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